

SoM-A5D35

User Manual

REV. 1.5

For use with PCB Revision 1 and greater SoMs

Copyright 2015,

EMAC, Inc.

Table of Contents

Disclaimer.....	4
1. Introduction	5
1.1. Features	5
2. Hardware	6
2.1. Specifications	6
2.2. Real-Time Clock.....	8
2.3. Watchdog Timer.....	8
2.4. External Connections	8
2.4.1. External Bus	8
2.4.2. JTAG	9
2.4.3. One-Wire / I2C	9
2.4.4. Ethernet.....	10
2.4.5. USB	10
2.4.6. SPI.....	11
2.4.7. MCI Multimedia Card	12
2.4.8. Serial Ports.....	12
2.4.9. I2S	13
2.4.10. CAN.....	13
2.4.11. GPIO	14
2.5. Power Connections	16
2.6. Boot Options.....	16
2.7. Serial Flash	17
3. Design Considerations.....	17
3.1. The EMAC SoM Carrier SoM-150ES.....	17
3.2. Power	17
3.2.1. Legacy.....	17
3.2.2. Analog Reference.....	17
3.2.3. Shutdown Logic Pins.....	18
3.2.4. Battery Backup	18
3.2.5. Analog Voltage	18

4. Software.....	19
3.1 Das U-Boot.....	19
3.2 Embedded Linux	19
3.2.1 Linux with Xenomai Real Time Extensions	19
3.2.2 Linux Packages	20
3.2.3 Linux Patches.....	20
3.3 Qt Creator.....	20
3.4 ARM EABI Cross Compiler	20

Disclaimer

EMAC Inc. does not assume any liability arising out of the application or use of any of its products or designs. Products designed or distributed by EMAC Inc. are not intended for, or authorized to be used in, applications such as life support systems or for any other use in which the failure of the product could potentially result in personal injury, death or property damage.

If EMAC Inc. products are used in any of the aforementioned unintended or unauthorized applications, Purchaser shall indemnify and hold EMAC Inc. and its employees and officers harmless against all claims, costs, damages, expenses, and attorney fees that may directly or indirectly arise out of any claim of personal injury, death or property damage associated with such unintended or unauthorized use, even if it is alleged that EMAC Inc. was negligent in the design or manufacture of the product.

EMAC Inc. reserves the right to make changes to any products with the intent to improve overall quality, without further notification.

1. Introduction



This document describes EMAC's SoM-A5D35 System on Module. The SoM-A5D35 is designed to be compatible with EMAC's 144-pin SODIMM form factor. This module is built around the ATMEL AT91SAMA5D35 microcontroller, which provides several of its key features.

The SoM-A5D35 has an onboard Ethernet PHY, 6 serial ports, 3 USB 2.0 ports, an I2S audio port, an MMC port, a RTC, a programmable clock synthesizer, onboard eMMC flash, Serial NOR Flash, and LPDDR2.

In addition to these standard SoM features, the SoM-A5D35 also features a fast 32-bit core, open source software support, and a wide range of controller IO pins.

1.1. Features

- **Small, 144 pin SODIMM form factor (2.66" x 1.5")**
- **Atmel ARM Cortex-A5 ATSAMA5D35 536MHz Processor**
- **10/100BaseT Ethernet with on-board PHY**
- **16 bit External Bus Interface**
- **6 Serial ports, one with full handshake and one with CTS/RTS handshake**
- **2 USB 2.0 (High Speed) Host ports**

- **1 USB 2.0 (High Speed) Device/Host port**
- **512 MB of LPDDR2**
- **4 GB of Resident eMMC Flash**
- **16 MB of Serial NOR Flash**
- **Battery-backed Real-Time Clock**
- **SD/MMC Flash Card Interface**
- **2 SPI ports**
- **2 I2C Ports**
- **1 I2S Audio Port**
- **2 CAN Bus Interfaces**
- **Timer/Counters and Pulse Width Modulation (PWM) ports**
- **4-Channel 12-bit Analog-to-Digital converter**
- **Typical power requirement less than 1 Watt**
- **JTAG for debug, including real-time trace**
- **FREE QT Creator IDE with GCC and GDB development tools**

2. Hardware

2.1. Specifications

- **CPU:** Embedded Atmel ATSAMA5D35 processor running at 536 MHz.
- **Flash:** 4GB eMMC Flash and 16MB of Serial NOR Flash.
- **RAM:** 512MB 133MHz LPDDR2.
- **Flash Disk:** 4-bit Parallel or SPI serial SDHC/MMC interface.
- **System Reset:** Supervisor with external Reset Button provision.
- **RTC:** Real-Time Clock/Calendar with battery-backed provision using 32-bit free running counter.
- **Timer/Counters:** 2, 3-channel, 32-bit timers/counters with capture, compare, and PWM.
- **Watchdog Timer:** External Watchdog Timer (MAX6747).
- **Digital I/O:** 32 General Purpose I/Os with 16 mA drive when used as an output
- **Analog I/O:** 4-channel, 12-bit Analog-to-Digital converter (ADC)
- **Power:** Power Management Controller allows selectively shutting down on-processor I/O functionality and running from a slow clock.
- **JTAG:** JTAG for debug, including real-time trace

- **CLOCKS:** PLL synthesized 8MHz, 200KHz, 14.3MHz clock outputs

1.1.1.1 Serial Interfaces

- **UARTS:** 6 serial TTL level serial ports with Auto RS485 and some with handshaking (each UART requires external RS level shifting).
- **SPI:** 2 High-Speed SPI ports with Chip Selects.
- **Audio:** I2S Synchronous Serial Controller with analog interface support
- **USB:** Dual USB 2.0 High Speed Host and single USB 2.0 High Speed Device ports

1.1.1.2 Ethernet Interface

- **MAC:** ATSAMA5D35 on chip MAC
- **PHY:** Micrel KSZ8081 low power PHY with software shutdown and slow clock modes
- **Interface:** IEEE 802.3u 10/100 BaseT Fast Ethernet (requires external magnetics and Jack)

1.1.1.3 Bus Interface

- Local ARM ATSAMA5D35 Bus accessible through card fingers provides 22 address lines, 16 data bus lines, and control lines.

1.1.1.4 Mechanical and Environmental

- **Dimensions:** SODIMM form factor with the length dimension extended (2.66" x 1.5")
- **Power Supply Voltage:** +3.3 Volts DC +/- 5%
- **Power Requirements:**
 - Typical 3.3 Volts @ 175 mA (less than 1 watt)
 - Maximum current draw during boot process: 210 mA
 - Constant busy loop: 180 mA
 - Idle system: 160 mA
 - Idle system with Ethernet PHY disabled: 65 mA
 - APM sleep mode with Ethernet PHY disabled: 9.5 mA
 - APM sleep mode with Ethernet PHY and USB disabled: 4.0 mA
 - APM sleep mode with Ethernet PHY enabled: 60 mA
- **Operating Temperature:** -40 to 85° C (-40 to 185° F), fan-less operation
- **Operating Humidity:** 0% to 90% relative humidity, non-condensing

2.2. Real-Time Clock

The SoM-A5D35 has an embedded Real-time Clock. Battery backup is provided from the carrier board using the VSTBY pin. The SoM-A5D35 will retain the RTT value register during reset and hence use it as a RTC. The RTC has the provision to set alarms that can interrupt the processor. For example the processor can be placed in sleep mode and then later awakened using the alarm function.

2.3. Watchdog Timer

The SoM-A5D35 provides an external Watchdog Timer/ Supervisor (MAX6747) with an extended watchdog timeout period of 1.42 seconds ($\pm 10\%$). Upon power-up the Watchdog is disabled and does not require pulsing. To start the Watchdog it must first be enabled. This is done by configuring port line PA24 as an output and setting it low in software. Once enabled, the Watchdog should be pulsed, using port line PA23, continually every 1.28 seconds or faster to prevent the Watchdog from timing out and resetting the module. If the user is using the watchdog to force a system reset, the watchdog may need up to 1.56 seconds of inactivity before the watchdog reset will occur. The watchdog is automatically disabled upon reset but it can also be disabled by setting PA24 high.

2.4. External Connections

The SoM-A5D35 connects to a carrier board containing its connectors, power supply and any expansion IO, through a standard ENIG-plated (Electroless Nickel Immersion Gold) SODIMM 144 pin connection (top half shown below).



The SoM model will fit in any standard 144-pin SODIMM socket. These connections are designed to be compatible with all EMAC 144-pin SoM products. See EMAC SoM 144-pin SODIMM Pinout Specification to see how other 144-pin SoMs pin-outs line up with the SoM-A5D35's pin-out.

The use of the SODIMM form-factor for EMAC's SoMs is a sound choice that has been proven rugged and reliable in the laptop market.

The remainder of this section describes the pin-out as it applies specifically to the SoM-A5D35 processor.

2.4.1. External Bus

The SoM-A5D35 provides a flexible external bus for connecting peripherals. The WKUP pin has a Maximum input voltage of 3.3V (pulled up on-module to 3.3V) and Shutdown has a maximum output voltage of 3.3V. The Flash WP for the Serial Flash is active-low and pulled up on-module.

SODIMM Pin#	SoM Pin Name	Processor Pin Name(s)	Description
100	GP_CS1	NCS1/PE27	General Purpose Processor Chip Select CS2
98	GP_CS2	NCS2/PE28	General Purpose Processor Chip Select CS4
108	GP_CS3	NCS3	General Purpose Processor Chip Select CS5
16	~OE	NRD	Read Signal

83	~WR	NWE	Write Signal
6	~RST_IN	SOM_RST_OUT	Processor Reset
43	~RST_OUT	NRST	Processor Reset
44	~EA	SHDN	Shutdown Control
85	Flash WP	Serial Flash WP	Serial Flash Write Protect
72	ALE/~TS	WKUP	Wake-Up Input
26,35,33,31, 28,109,111, 113,10,12,18 ,14,37,5,11,9 ,7,13,97,17, 15,104	A0-A21	A0-A21	Address Bus
29,27,25,22, 23,21,19,20, 8,24,34,70, 77,81,84,86	D0-D15	D0-D15	Data Bus

2.4.2. JTAG

The SoM specification allows for access to the JTAG lines for the ATSAMA5D35 processor. These connections will allow the Flash to be programmed in-circuit via a program running from the processor and also the capability to debug software.

Processor JTAG

SODIMM Pin#	SoM Pin Name	Processor Pin Name(s)	Description
139	JTAG_TCK	TCK/SWCLK	JTAG clock
137	JTAG_TDI	TDI	JTAG serial in
138	JTAG_TDO	TDO	JTAG serial out
140	JTAG_TMS	TMS/SWDIO	JTAG operation mode
112	JTAG_TRST	NTRST	Test Reset Signal

2.4.3. One-Wire / I2C

The SoM specification calls for a one-wire port. Since the SoM-A5D35 does not have a one-wire port, this line is not connected for One-Wire Operation. The ATSAMA5D35 processor does provide an I2C bus and so these pins are dedicated to that function although they can also be used as GPIOs.

One-Wire / I2C Port

SODIMM Pin#	SoM Pin Name	Processor Pin Name(s)	Description
116	LOCAL1W /SCL	TWCK0/PA31	I2C Clock
88	SDA	TWD0/PA30	I2C Data

2.4.4. Ethernet

The SoM-A5D35 provides a Micrel KSZ8081 Low Power Ethernet RMII PHY IC on board. Carrier designers need only run these lines through the appropriate magnetics layer to have a functional Ethernet connection. Remember the RX and TX lines are differential pairs and need to be routed as such.

The LED/configuration pins' state at reset determines the Ethernet's configuration (10-baseT, 100-base-T, autoconfig) and the function of the LED's. The SoM-100ES and the SoM-150ES pull them all high, which configures the chip for network autoconfig, with LED0 functioning as active low link, and LED1 functioning as active low Rx Activity (Refer to Carrier schematics).

The Ethernet PHY can be put into a low power mode by writing directly to the MAC via software.

Additional power can be saved by turning off the PHY Oscillator. This is done by setting GPIO PC10 low. Make sure to send software commands to the PHY to put it into slow clock and power-down mode before shutting off the Oscillator. When restoring the PHY first turn the Oscillator on and disable slow clock mode before accessing the PHY.

Ethernet

SODIMM Pin#	SoM Pin Name	KSZ8081 Pin Name	Description
89	LED_LINK/CFG_1	LED_0 NWAYEN	Ethernet Link LED Configuration Pin
90	LED_RX/CFG_2	LED_1 SPEED	Ethernet Activity LED Configuration pin
94	Ethernet_Rx-	RXM	Low differential Ethernet receive line
92	Ethernet_Rx+	RXP	High differential Ethernet receive line
93	Ethernet_Tx-	TXM	Low differential Ethernet transmit line
91	Ethernet_Tx+	TXP	High differential Ethernet transmit line

2.4.5. USB

The SoM-A5D35 provides 2 High speed USB 2.0 Host ports and 1 High Speed USB 2.0 Device/Host port. The USB Device/Host port can be used as an "On-The-Go"-like port on custom carriers. The Device/Host port is connected to a USB Type B connector on the SoM-100ES and SoM-150ES carrier boards.

USB

SODIMM Pin#	SoM Pin Name	Processor Pin Name(s)	Description
64	USB1_D+	HHSDPB	Host, High Speed USB 1
66	USB1_D-	HHSDMB	Host, High Speed USB 1
65	USB2_D+	HHSDPC	Host, High Speed USB 2
67	USB2_D-	HHSDMC	Host, High Speed USB 2
60	USB3/OTG_D-	H/DHSDMA	Device/Host, HS USB 3
61	USB3/OTG_D+	H/DHSDPA	Device/Host, HS USB 3
45	USB_OTG_VBUS	AD10/PD30	USB OTG VBUS Detect

2.4.6. SPI

The ATSAM5D35 processor provides a dual (SPI0 and SPI1) SPI module for communicating with peripheral devices. On the SoM the SPI0 bus is already connected to the serial flash, which uses SPI0_NPCS0 (SPI0_NPCS0 is not brought out to the card fingers). The first Table below lists the lines for the #0 SPI module. The SoM pin specification allows for three SPI chip selects. The SPI chip selects available to the card edge are SPI0_NPCS1, SPI0_NPCS2, and SPI0_NPCS3. The second Table below lists the lines for the #1 SPI module.

Serial Peripheral Interface

SODIMM Pin#	SoM Pin Name	Processor Pin Name(s)	Description
122	SPI0_MI	SPI0_MISO/PD10	SPI0 serial data in
121	SPI0_MO	SPI0_MOSI/PD11	SPI0 serial data out
120	SPI0_SCK	SPI0_SPCK/PD12	SPI0 serial clock out
123	SPI0_CS0	SPI0_NPCS1/PD14	SPI0 slave select line 0
124	SPI0_CS1	SPI0_NPCS2/PD15	SPI0 slave select line 1
110	SPI0_CS2	SPI0_NPCS3/PD16	SPI0 slave select line 2

SODIMM Pin#	SoM Pin Name	Processor Pin Name(s)	Description
133	SPI1_MISO/GPIO	SPI1_MISO/PC22	SPI1 serial data in / GPIO
134	SPI1_MOSI/GPIO	SPI1_MOSI/PC23	SPI1 serial data out / GPIO
135	SPI1_SCK/GPIO	SPI1_SPCK/PC24	SPI1 serial clock out / GPIO
136	SPI1_NPCS0/GPIO	SPI1_NPCS2/TWCK1/PC27	SPI1 slave select line 0 / GPIO
105	SPI1_NPCS1/GPIO	SPI1_NPCS1/TWD1/PC26	SPI1 slave select line 1 / GPIO

2.4.7. MCI Multimedia Card

The ATSAMA5D35 processor provides a 4-bit MMC/SD card interface using the MC lines.

The SoM-100ES Carrier board uses a serial SPI based MMC/SD interface. The SoM-A5D35 could be programmed to use this serial interface, however the drivers provided are written to utilize the 4-bit interface and as such required the SoM-150ES Carrier board to use these drivers.

MMC/SD Card Interface

SODIMM Pin#	SoM Pin Name	Processor Pin Name(s)	Description
54	MCI_CK	MCI0_CK/PB24	MCI Clock
51	MCI_CDA	MCI0_CDA/PB19	MCIA Command
50	MCI_DA0	MCI0_DA0/PB20	MCIA D0
55	MCI_DA1	MCI0_DA1/PB21	MCIA D1
56	MCI_DA2	MCI0_DA2/PB22	MCIA D2
57	MCI_DA3	MCI0_DA3/PB23	MCIA D3
42	MCI_CD	TIOB1/PC13	MCIA Card Detect

2.4.8. Serial Ports

The SoM-144 pin specification has the provision for 3 serial ports. However, the ATSAMA5D35 provides 6 serial ports so the 3 additional serial ports are accommodated through the use of alternate SoM pins. UART1 on the ATSAMA5D35 processor provides handshaking pins, however the RING, DSR, DCD, and DTR signals are not available on the processor and are generated by software using GPIOs.

Serial Ports

SODIMM Pin#	SoM Pin Name	Processor Pin Name(s)	Description
71	COMA_RXD	RXD0/PD17	UART0 Receive/GPIO
73	COMA_TXD	TXD0/PD18	UART0 Transmit/GPIO
38	COMB_RXD	RXD2/PE25	UART2 Receive/GPIO
36	COMB_TXD	TXD2/PE26	UART2 Transmit/GPIO
82	COMB_RTS/GPIO	RTS2/PE24	UART2 RTS/GPIO
78	COMB_CTS/GPIO	CTS2/PE23	UART2 CTS/GPIO
103	COMC_RXD	RXD1/PB28	UART1 Receive/GPIO
102	COMC_TXD	TXD1/PB29	UART1 Transmit/GPIO
107	COMC_DSR/GPIO	PWMH1/PA22	UART1 DSR /GPIO
106	COMC_DTR/GPIO	PWMH2/PB8	UART1 DTR/GPIO
76	COMC_RI/GPIO	PWMH3/PB12	UART1 RING/GPIO
30	COMC_DCD/GPIO	PWMH0/PA20	UART1 DCD/GPIO
39	COMC_RTS/GPIO	RTS1/PB27	UART1 RTS/GPIO
79	COMC_CTS/GPIO	CTS1/PB26	UART1 CTS/GPIO

Additional Serial Ports

SODIMM Pin#	SoM Pin Name	Processor Pin Name(s)	Description
46	Debug RXD	DRXD/PB30	Debug Receive / GPIO
47	Debug TXD	DTXD/PB31	Debug Transmit / GPIO
49	COMD RXD	RXD3/PE18	UART3 Receive / GPIO
48	COMD TXD	TXD3/PE19	UART3 Transmit / GPIO
88	SDA	URXD1/PA30	USART1 RXD / GPIO
116	LOCAL1W /SCL /SCL	UTXD1/PA31	USART1 TXD / GPIO

2.4.9. I2S

The SoM-A5D35 provides an I2S serial interface for connecting to an audio codec.

I2S

SODIMM Pin#	SoM Pin Name	Processor Pin Name(s)	Description
87	I2S_TXCK	TK1/PB2	Transmit Clock / GPIO
80	I2S_LRCK	TF1/PB3	Transmit Frame / GPIO
125	I2S_RXD	RD1/PB11	Serial Receive Data / GPIO
126	I2S_TXD	TD1/PB6	Serial Transmit Data / GPIO
128	I2S_RF	RF1/PB10	Receive Frame / GPIO
127	I2S_RXCK	RK1/PB7	Receive Clock / GPIO

2.4.10. CAN

The ATSAMA5D35 has two CAN controllers that are brought out to the SoM card edge. One is defined by the SoM specification and the second can be utilized instead of the SPI chip selects. The SoM specified CAN port can be used as GPIO if desired.

CAN Port

SODIMM Pin#	SoM Pin Name	Processor Pin Name(s)	Description
96	CANTX	CANTX1/PB15	CAN Transmit / GPIO
95	CANRX	CANRX1/PB14	CAN Receive / GPIO

Additional CAN Port

SODIMM Pin#	SoM Pin Name	Processor Pin Name(s)	Description
123	SPI0_CS0	CANRX0/SPI0_NPCS1/PD14	CAN Receive / SPI Chip Select 1
124	SPI0_CS1	CANTX0/SPI0_NPCS2/PD15	CAN Transmit / SPI Chip select 2

2.4.11. GPIO

This section provides for the SoM general purpose IO section. All of these pins can be configured to be general-purpose digital ports. They can also be configured to take advantage of several of the functions of the ATSAM5D35's internal silicon. All of the internal A/D ports are brought out here, as well as all of the available IRQs, the second SPI and the pins for general-purpose timer/counters.

Interrupts:

The ATSAM5D35 is capable of using any GPIO pin as an interrupt as well as the pins that are labeled IRQ. The 144-Pin SoM Specification defines 3 IRQs.

Interrupt Lines

SODIMM Pin#	SoM Pin Name	Processor Pin Name(s)	Description
75	IRQA/GPIO_0	FIQ/PC31	Interrupt A / GPIO 0
32	IRQB/GPIO_1	IRQ/PWML1/PE31	Interrupt B / GPIO 1
40	IRQC/GPIO_2	TCLK1/PC16	Interrupt C / GPIO 2

A/D:

The ATSAM5D35 Analog to Digital pins provides 4 channels of 12-bit resolution with a 1 us conversion time. With the enhanced DSP extensions, this can make quite a capable signal processor. The Analog to Digital Reference Voltage is enabled by default, but can be controlled by PA25. PA25 configured as an input disables the reference, or it can be enabled by configuring it as an output and driving it low. To disable

Analog to Digital Converters

SODIMM Pin#	SoM Pin Name	Processor Pin Name(s)	Description
129	AD1/GPIO_5	AD0/PD20	ADC CH1 / GPIO 5
130	AD2/GPIO_6	AD1/PD21	ADC CH2 / GPIO 6
131	AD3/GPIO_7	AD2/PD22	ADC CH3 / GPIO 7
132	AD4/GPIO_8	AD3/PD23	ADC CH4 / GPIO 8

Timer/Counters:

The general-purpose Timer/Counter (TC) module on the ATSAMA5D35 is comprised of six 32-bit timer/counter channels with independently programmable input capture or output compare lines. These can be used for a wide variety of timed applications, including counters and PWM.

Timers/Counters

SODIMM Pin#	SoM Pin Name	Processor Pin Name(s)	Description
117	CLK1/GPIO_3	PCK2/PC15	Programmable Clock / GPIO 3
127	CLK2/GPIO_4	RK1/PB7	Programmable Clock / GPIO 4
114	PWM1/GPIO_14	TIOA1/PC12	PWM / Clock / GPIO 14
115	PWM2/GPIO_15	TIOB0/PD6	PWM / Clock / GPIO 15

For more information on the A/D and Timer functions of the ATSAMA5D35 processor, users are referred to the TC section of the *ATSAMA5D35 User's Manual*.

Module Status LED:

A Green general purpose Status LED is connected to PA26.

General Purpose IO

SODIMM Pin#	SoM Pin Name	Processor Pin Name(s)	Description
40	IRQC/GPIO_2	TCLK1/PC16	Interrupt C / GPIO 2
75	IRQA/GPIO_0	FIQ/PC31	Interrupt A / GPIO 0
32	IRQB/GPIO_1	IRQ/PWML1/PE31	Interrupt B / GPIO 1
117	CLK1/GPIO_3	PCK2/PC15	Programmable Clock / GPIO 3
127	CLK2/GPIO_4	RK1/PB7	Programmable Clock / GPIO 4
129	AD1/GPIO_5	AD0/PD20	ADC CH1 / GPIO 5
130	AD2/GPIO_6	AD1/PD21	ADC CH2 / GPIO 6
131	AD3/GPIO_7	AD2/PD22	ADC CH3 / GPIO 7
132	AD4/GPIO_8	AD3/PD23	ADC CH4 / GPIO 8
133	SPI0_MI/GPIO_9	SPI1_MISO/PC22	SPI1 Master In / GPIO 9
134	SPI0_MO/GPIO_10	SPI1_MOSI/PC23	SPI1 Master Out / GPIO 10
135	SPI0_SCK/GPIO_11	SPI1_SPCK/PC24	SPI1 Serial Clock / GPIO 11
136	SPI0_CS0/GPIO_12	SPI1_NPCS2/TWCK1/PC27	SPI1 Chip Select 0 / GPIO 12
105	SPI0_CS1/GPIO_13	SPI1_NPCS1/TWD1/PC26	SPI1 Chip Select 1 / GPIO 13
114	PWM1/GPIO_14	TIOA1/PC12	PWM / Clock / GPIO 14
115	PWM2/GPIO_15	TIOB0/PD6	PWM / Clock / GPIO 15
48	COMD TXD	TXD3/PE19	SER E Transmit / GPIO
49	COMD RXD	RXD3/PE18	SER E Receive / GPIO

2.5. Power Connections

The SoM-A5D35 requires a 3.3V supply for the Bus and I/O voltages. The 1.2V core voltage is regulated on module from the 3.3V. The on-processor RTC also requires 3.3V and supplied by either a battery or the 3.3V power rail. Unlike some other modules no other supply voltage other than 3.3V is required.

SODIMM Pin#	SoM Pin Name	Processor Pin Name(s)	Description
3,4,141,142	3.3VCC	3.3VCC	3.3 Volt I/O voltage to the processor
1,2,52,53,58,59,62,63,68,69,143, 1144	GND	GND	Ground
119	VSTBY	VDDBU battery backup	Voltage standby, this is the backup voltage provided to the internal RTC of the processor. If RTC readings are not important for the application, this can be attached to the 3.3V rail.
118	ALT_VCC	Not Used	Not Required
101	AV_VCC	Not Used	Analog power. This is not required for the SoM-A5D35
99	V_REF	Not Used	No external Analog Reference voltage is required for the SoM-A5D35.

2.6. Boot Options

The SoM specification provides two pins for boot time configuration. On the SoM-A5D35, these are BMS and Flash Disable. The Boot Mode Select (BMS) pin allows the SoM-A5D35 to be low-level booted from either its internal ROM or external (carrier-resident) NOR flash.

The Flash Disable pin should be tied to GND to enable the Serial Flash and the NAND Flash (if present on carrier).

The Module can high-level boot from either the Serial Flash or the eMMC (selected through the low-level bootloader). It is recommended to high-level boot from the Serial Flash.

SODIMM Pin#	SoM Pin Name	Processor Pin Name(s)	Description
41	BOOT_OPTION1	BMS	Boot Mode Select
74	BOOT_OPTION2	Flash Disable	Serial Flash Disable, Not Connected to Processor

2.7. Serial Flash

The Serial Flash is connected to SPI0 and uses SPI0_NPCS0 to enable it. The Serial Flash also has a Write-Protect Provision. To Write-Protect the Serial Flash pull SoM pin# 85 low. SoM pin# 85 is pulled up by a 10K ohm resistor on the module. If this feature is required it would be implemented on the carrier as a jumper or an I/O line. The Serial flash may ne disabled in order to force the processor to boot from the internal ROM by pulling BOOT_OPTION2 (SoM pin# 74) high.

3. Design Considerations

One of the goals of the SoM-A5D35 is to provide a modular, flexible and inexpensive solution capable of delivering high-end microcontroller performance with low power requirements.

3.1. The EMAC SoM Carrier SoM-150ES

EMAC provides an off-the-shelf carrier for the SoM-A5D35 module, the SoM-150ES, which provides power to SoM modules and provides them with an extended range of I/O. This board comes with full schematics and BOM, and can be used as is, or as a reference for a customer's own design.

http://www.emacinc.com/products/system_on_module/SoM-150ES

EMAC also offers a semi-custom engineering service. By modifying an existing design, EMAC can offer quick-turn, low-cost engineering, for your specific application.



3.2. Power

The SoM-A5D35 requires a voltage of 3.3V at 250mA. For a bare-bones population, users can get away with using only 3.3V, and simply provide this to all the voltage inputs listed in Power Connections section. This however, will not provide battery backup for the RTC.

3.2.1. Legacy

ALT_VCC is a legacy connection, required to support the SoM-400EM and may be used in future SoM modules. If general SoM compatibility is not an issue then this can be tied to 3.3V. The SoM-A5D35 does not use this connection.

3.2.2. Analog Reference

No external Analog Reference voltage (VREF) is required for the SoM-A5D35. An on-module 2.5V reference is provided. Analog input range is therefore 0 to 2.5V. This pin is normally a No Connect on the Module. This Reference uses power and therefore can be turned off by setting GPIO Port Line PA25 as an input, thus conserving about 3 ma.

3.2.3. Shutdown Logic Pins

The SHDN is a digital output only with a logical high of 3.3V, which is driven by the Shutdown Controller on the processor.

The WKUP pin has a Maximum input voltage of 3.3V.

Both of these pins are connected directly to the processor.

3.2.4. Battery Backup

The SoM-A5D35 contains 3 potentially non-volatile memory areas, the eMMC flash, the real-time clock (RTC), and the serial flash of the processor. The flash is always non-volatile, the real-time clock requires a backup voltage to maintain its data. This backup voltage comes from the VSTBY pin, and should be connected to 3.3 volts.

The RTC will draw approximately 10 uA when the processor is not powered by the 3.3V supply. The Static current can rise to 18uA if the temperature increases to 85° C. When the module is powered no current is drawn from the backup battery supply. If the RTC is not needed, this can be tied to 3.3V.

The SoM-100ES and SoM-150ES provide battery backup voltage through a socketed BR2032, which is a standard 3V 190mA/H 20MM coin battery that can be picked up from most electronics stores.

3.2.5. Analog Voltage

When designing power for the Analog subsystem there are 4 major considerations, range and accuracy output drive, and rise time.

- **Range**
The AV_VCC pin normally provides the range. However on the SoM-A5D35 the Analog VCC (VDDANA) is directly connected to filtered 3.3V. The power supplied to the analog subsystem limits the range of voltages that can be accurately measured. The internal analog converters cannot measure a voltage higher than the reference voltage provided on the SoM. The Analog input range is 0 to 2.5V.
- **Accuracy**
The accuracy of the A/D converters is determined by the V_REF pin, which provides the reference voltage to the analog subsystem. The stability of the voltage between this pin and ground will affect the accuracy of the subsystem's measurements. No external Analog Reference voltage is required for the SoM-A5D35. An on-module 2.5V reference is provided. Analog input range is therefore 0 to 2.5V.

4. Software

The SoM-A5D35 offers a wide variety of software support from both open source and proprietary sources. The hardware core was designed to be software compatible with the Atmel AT91SAMA5D3x-EK reference design, which is supported by Linux.

For more information on Linux Software Support, please visit the EMAC Wiki Software Section at:

http://wiki.emacinc.com/wiki/product_wiki

3.1 Das U-Boot

EMAC utilizes Das U-Boot for its ARM based products. U-Boot is an open source/cross-architecture platform independent bootloader. It supports reading and writing to the flash, auto-booting, environmental variables, and TFTP. Das U-boot can be used to upload and run and/or reflash the OS or to run stand-alone programs without an OS. Products are shipped with a valid MAC address installed in flash in the protected U-boot environmental variable “ethaddr”. At boot time U-Boot automatically stores this address in a register within the MAC, which effectively provides it to any OS loaded after that point.

3.2 Embedded Linux

EMAC Open Embedded Linux is an open source Linux distribution for use in embedded systems. The EMAC OE Linux Build is based on the Open Embedded (www.openembedded.org) Linux build system. Open Embedded is a superior Linux distribution for embedded systems. Custom Linux builds are also available on request.

The distribution contains everything a user could expect from a standard Linux kernel: powerful networking features, advanced file system support, security, debugging utilities, and countless other features.

The basic root file system includes:

- Busybox
- Hotplugging support
- APM utilities for power management
- Openssh SSH server
- lighttpd HTTP server
- JFFS2 or EXT4 file system with utilities

3.2.1 Linux with Xenomai Real Time Extensions

Xenomai provides real time extensions to the kernel and can be used to schedule tasks with hard deadlines and μ s latencies. The Xenomai build is an additional module that can be added to the standard Linux kernel and is available for a one-time inexpensive support/installation fee.

<http://www.xenomai.org/>

3.2.2 Linux Packages

EMAC provides support for many Linux Packages such as: PHP, SQLite, Perl, SNMP, DHCP Server, etc. As with the Xenomai Package, other Packages can be added to the standard Linux file system and are available for a one-time inexpensive support/installation fee.

3.2.3 Linux Patches

In addition to standard Embedded Linux support, EMAC has released a number of patches and device drivers from the open source community and from internal EMAC engineering into its standard distribution. Along with kernel patches, EMAC provides the binaries for the kernel and root file system.

3.3 Qt Creator

Qt Creator is a cross-platform IDE (Integrated Development Environment) tailored to the needs of Qt developers but works well for Headless applications as well. EMAC provides sample code as projects that can be imported into Qt Creator. Qt Creator supports remote deployment and source debugging.

<https://qt-project.org/wiki/Category:Tools::QtCreator>

3.4 ARM EABI Cross Compiler

The popular open source gcc compiler has a stable build for the ARM family. EMAC uses the 4.9.1 version of the ARM EABI compiler. The Embedded Linux kernel and EMAC Qt Creator projects use this compiler for building ARM stand alone, and OS specific binaries. The EMAC Qt Creator provides source level debugging over Ethernet or serial using gdbserver. The Linux binaries for the ARM EABI cross compiler are available online along with the SDK. See the EMAC wiki for further information.